

# NAG C Library Function Document

## nag\_dsptrs (f07pec)

### 1 Purpose

nag\_dsptrs (f07pec) solves a real symmetric indefinite system of linear equations with multiple right-hand sides,  $AX = B$ , where  $A$  has been factorized by nag\_dsptrf (f07pdc), using packed storage.

### 2 Specification

```
void nag_dsptrs (Nag_OrderType order, Nag_UptoType uplo, Integer n, Integer nrhs,
                 const double ap[], const Integer ipiv[], double b[], Integer pdb,
                 NagError *fail)
```

### 3 Description

To solve a real symmetric indefinite system of linear equations  $AX = B$ , this function must be preceded by a call to nag\_dsptrf (f07pdc) which computes the Bunch–Kaufman factorization of  $A$  using packed storage.

If **uplo** = **Nag\_Upper**,  $A = PUDU^T P^T$ , where  $P$  is a permutation matrix,  $U$  is an upper triangular matrix and  $D$  is a symmetric block diagonal matrix with 1 by 1 and 2 by 2 blocks; the solution  $X$  is computed by solving  $PUDY = B$  and then  $U^T P^T X = Y$ .

If **uplo** = **Nag\_Lower**,  $A = PLDL^T P^T$ , where  $L$  is a lower triangular matrix; the solution  $X$  is computed by solving  $PLDY = B$  and then  $L^T P^T X = Y$ .

### 4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

### 5 Parameters

1: **order** – Nag\_OrderType *Input*

*On entry:* the **order** parameter specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = **Nag\_RowMajor**. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.

*Constraint:* **order** = **Nag\_RowMajor** or **Nag\_ColMajor**.

2: **uplo** – Nag\_UptoType *Input*

*On entry:* indicates how  $A$  has been factorized as follows:

if **uplo** = **Nag\_Upper**,  $A = PUDU^T P^T$ , where  $U$  is upper triangular;  
 if **uplo** = **Nag\_Lower**,  $A = PLDL^T P^T$ , where  $L$  is lower triangular.

*Constraint:* **uplo** = **Nag\_Upper** or **Nag\_Lower**.

3: **n** – Integer *Input*

*On entry:*  $n$ , the order of the matrix  $A$ .

*Constraint:* **n**  $\geq 0$ .

4:	<b>nrhs</b> – Integer	<i>Input</i>
<i>On entry:</i> $r$ , the number of right-hand sides.		
<i>Constraint:</i> $\mathbf{nrhs} \geq 0$ .		
5:	<b>ap</b> [ <i>dim</i> ] – const double	<i>Input</i>
<b>Note:</b> the dimension, $dim$ , of the array <b>ap</b> must be at least $\max(1, \mathbf{n} \times (\mathbf{n} + 1)/2)$ .		
<i>On entry:</i> details of the factorization of $A$ stored in packed form, as returned by nag_dsptrf (f07pdc).		
6:	<b>ipiv</b> [ <i>dim</i> ] – const Integer	<i>Input</i>
<b>Note:</b> the dimension, $dim$ , of the array <b>ipiv</b> must be at least $\max(1, \mathbf{n})$ .		
<i>On entry:</i> details of the interchanges and the block structure of $D$ , as returned by nag_dsptrf (f07pdc).		
7:	<b>b</b> [ <i>dim</i> ] – double	<i>Input/Output</i>
<b>Note:</b> the dimension, $dim$ , of the array <b>b</b> must be at least $\max(1, \mathbf{pdb} \times \mathbf{nrhs})$ when <b>order</b> = Nag_ColMajor and at least $\max(1, \mathbf{pdb} \times \mathbf{n})$ when <b>order</b> = Nag_RowMajor.		
If <b>order</b> = Nag_ColMajor, the $(i, j)$ th element of the matrix $B$ is stored in <b>b</b> [( $j - 1$ ) $\times$ <b>pdb</b> + $i - 1$ ] and if <b>order</b> = Nag_RowMajor, the $(i, j)$ th element of the matrix $B$ is stored in <b>b</b> [( $i - 1$ ) $\times$ <b>pdb</b> + $j - 1$ ].		
<i>On entry:</i> the $n$ by $r$ right-hand side matrix $B$ .		
<i>On exit:</i> the $n$ by $r$ solution matrix $X$ .		
8:	<b>pdb</b> – Integer	<i>Input</i>
<i>On entry:</i> the stride separating matrix row or column elements (depending on the value of <b>order</b> ) in the array <b>b</b> .		
<i>Constraints:</i>		
if <b>order</b> = Nag_ColMajor, <b>pdb</b> $\geq \max(1, \mathbf{n})$ ; if <b>order</b> = Nag_RowMajor, <b>pdb</b> $\geq \max(1, \mathbf{nrhs})$ .		
9:	<b>fail</b> – NagError *	<i>Output</i>
The NAG error parameter (see the Essential Introduction).		

## 6 Error Indicators and Warnings

### NE\_INT

On entry, **n** =  $\langle value \rangle$ .  
 Constraint: **n**  $\geq 0$ .

On entry, **nrhs** =  $\langle value \rangle$ .  
 Constraint: **nrhs**  $\geq 0$ .

On entry,  **pdb** =  $\langle value \rangle$ .  
 Constraint:  **pdb** > 0.

### NE\_INT\_2

On entry,  **pdb** =  $\langle value \rangle$ , **n** =  $\langle value \rangle$ .  
 Constraint:  **pdb**  $\geq \max(1, \mathbf{n})$ .

On entry,  **pdb** =  $\langle value \rangle$ , **nrhs** =  $\langle value \rangle$ .  
 Constraint:  **pdb**  $\geq \max(1, \mathbf{nrhs})$ .

**NE\_ALLOC\_FAIL**

Memory allocation failed.

**NE\_BAD\_PARAM**

On entry, parameter  $\langle value \rangle$  had an illegal value.

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

## 7 Accuracy

For each right-hand side vector  $b$ , the computed solution  $x$  is the exact solution of a perturbed system of equations  $(A + E)x = b$ , where

if **uplo** = **Nag\_Upper**,  $|E| \leq c(n)\epsilon P|U||D||U^T|P^T$ ;

if **uplo** = **Nag\_Lower**,  $|E| \leq c(n)\epsilon P|L||D||L^T|P^T$ ,

$c(n)$  is a modest linear function of  $n$ , and  $\epsilon$  is the **machine precision**.

If  $\hat{x}$  is the true solution, then the computed solution  $x$  satisfies a forward error bound of the form

$$\frac{\|x - \hat{x}\|_\infty}{\|x\|_\infty} \leq c(n) \operatorname{cond}(A, x)\epsilon$$

where  $\operatorname{cond}(A, x) = \| |A^{-1}| |A| |x| \|_\infty / \|x\|_\infty \leq \operatorname{cond}(A) = \| |A^{-1}| |A| \|_\infty \leq \kappa_\infty(A)$ . Note that  $\operatorname{cond}(A, x)$  can be much smaller than  $\operatorname{cond}(A)$ .

Forward and backward error bounds can be computed by calling **nag\_dsprfs** (f07phc), and an estimate for  $\kappa_\infty(A)$  ( $= \kappa_1(A)$ ) can be obtained by calling **nag\_dspcon** (f07pgc).

## 8 Further Comments

The total number of floating-point operations is approximately  $2n^2r$ .

This function may be followed by a call to **nag\_dsprfs** (f07phc) to refine the solution and return an error estimate.

The complex analogues of this function are **nag\_zhptrs** (f07psc) for Hermitian matrices and **nag\_zsptrs** (f07qsc) for symmetric matrices.

## 9 Example

To solve the system of equations  $AX = B$ , where

$$A = \begin{pmatrix} 2.07 & 3.87 & 4.20 & -1.15 \\ 3.87 & -0.21 & 1.87 & 0.63 \\ 4.20 & 1.87 & 1.15 & 2.06 \\ -1.15 & 0.63 & 2.06 & -1.81 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} -9.50 & 27.85 \\ -8.38 & 9.90 \\ -6.07 & 19.25 \\ -0.96 & 3.93 \end{pmatrix}.$$

Here  $A$  is symmetric indefinite, stored in packed form, and must first be factorized by **nag\_dsptrf** (f07pdc).

### 9.1 Program Text

```
/* nag_dsptrs (f07pec) Example Program.
*
* Copyright 2001 Numerical Algorithms Group.
*
* Mark 7, 2001.
*/
```

```

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf07.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    Integer ap_len, i, j, n, nrhs, pdb;
    Integer exit_status=0;
    NagError fail;
    Nag_UptoType uplo_enum;
    Nag_OrderType order;
    /* Arrays */
    Integer *ipiv=0;
    char uplo[2];
    double *ap=0, *b=0;

#ifdef NAG_COLUMN_MAJOR
#define A_UPPER(I,J) ap[J*(J-1)/2 + I - 1]
#define A_LOWER(I,J) ap[(2*n-J)*(J-1)/2 + I - 1]
#define B(I,J) b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
#else
#define A_LOWER(I,J) ap[I*(I-1)/2 + J - 1]
#define A_UPPER(I,J) ap[(2*n-I)*(I-1)/2 + J - 1]
#define B(I,J) b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);
    Vprintf("f07pec Example Program Results\n\n");

    /* Skip heading in data file */
    Vscanf("%*[^\n] ");
    Vscanf("%ld%ld%*[^\n] ", &n, &nrhs);
    ap_len = n*(n+1)/2;
#ifdef NAG_COLUMN_MAJOR
    pdb = n;
#else
    pdb = nrhs;
#endif

    /* Allocate memory */
    if ( !(ap = NAG_ALLOC(ap_len, double)) ||
        !(ipiv = NAG_ALLOC(n, Integer)) ||
        !(b = NAG_ALLOC(n * nrhs, double)) )
    {
        Vprintf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

    /* Read A and B from data file */
    Vscanf(" ' %ls '%*[^\n] ", uplo);
    if (*(unsigned char *)uplo == 'L')
        uplo_enum = Nag_Lower;
    else if (*(unsigned char *)uplo == 'U')
        uplo_enum = Nag_Upper;
    else
    {
        Vprintf("Unrecognised character for Nag_UptoType type\n");
        exit_status = -1;
        goto END;
    }
    if (uplo_enum == Nag_Upper)
    {
        for (i = 1; i <= n; ++i)
        {
            for (j = i; j <= n; ++j)

```

```

        Vscanf("%lf", &A_UPPER(i,j));
    }
    Vscanf("%*[^\n] ");
}
else
{
    for (i = 1; i <= n; ++i)
    {
        for (j = 1; j <= i; ++j)
            Vscanf("%lf", &A_LOWER(i,j));
    }
    Vscanf("%*[^\n] ");
}
for (i = 1; i <= n; ++i)
{
    for (j = 1; j <= nrhs; ++j)
        Vscanf("%lf", &B(i,j));
}
Vscanf("%*[^\n] ");

/* Factorize A */
f07pdc(order, uplo_enum, n, ap, ipiv, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from f07pdc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
/* Compute solution */
f07pec(order, uplo_enum, n, nrhs, ap, ipiv, b, pdb, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from f07pec.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
/* Print solution */
x04cac(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, nrhs, b, pdb,
        "Solution(s)", 0, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from x04cac.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
END:
if (ap) NAG_FREE(ap);
if (ipiv) NAG_FREE(ipiv);
if (b) NAG_FREE(b);
return exit_status;
}

```

## 9.2 Program Data

```

f07pec Example Program Data
 4  2                      :Values of N and NRHS
 'L'                      :Value of UPLO
 2.07
 3.87 -0.21
 4.20  1.87   1.15
 -1.15  0.63   2.06  -1.81  :End of matrix A
 -9.50  27.85
 -8.38  9.90
 -6.07  19.25
 -0.96  3.93          :End of matrix B

```

### 9.3 Program Results

f07pec Example Program Results

```
Solution(s)
      1          2
1   -4.0000    1.0000
2   -1.0000    4.0000
3    2.0000    3.0000
4    5.0000    2.0000
```

---